

# How appropriate is optimism for Interface Automata

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# Interface-based design

- Interfaces abstract from details like data
- Focus on behavioural type and communication
- Analysis of errors in communication
- Refinement-/Implementation-relation
  - Refinement of components  $\rightarrow$  refinement of system
  - $\rightarrow$  precongruence

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- Automata with disjoint inputs, outputs and internal actions
- Composition of ‘compatible’ Automata  
( $I_1 \cap I_2 = \emptyset = O_1 \cap O_2$ )
- Shared actions: input of the one and output of the other automaton
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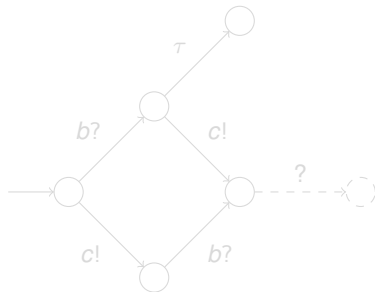
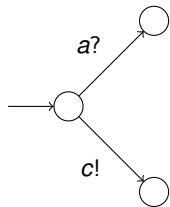
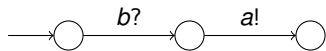
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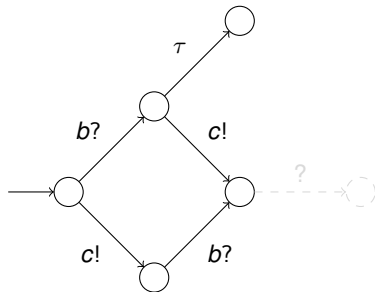
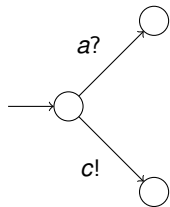
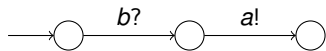
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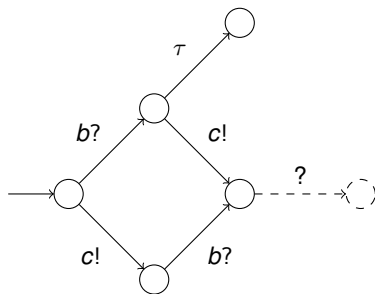
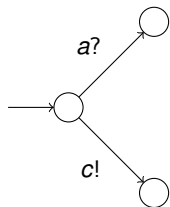
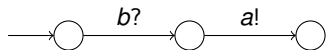


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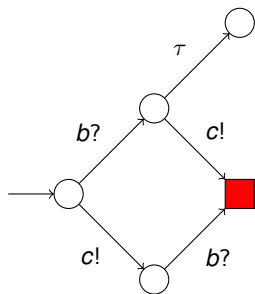
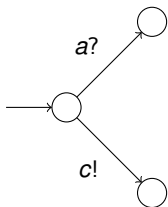
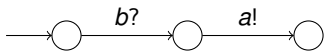




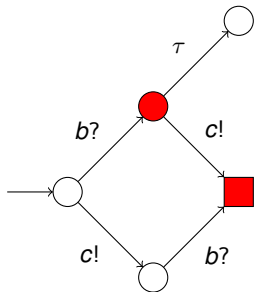
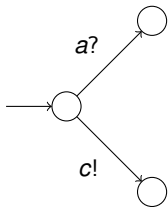
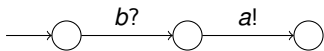
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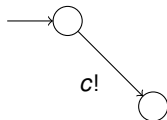
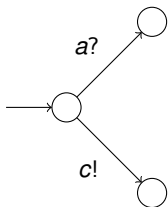
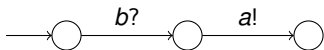
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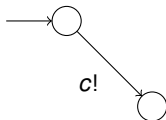
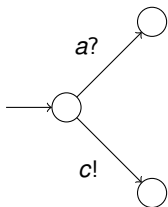
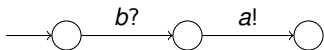
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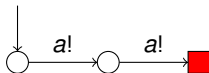


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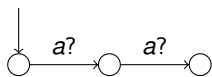
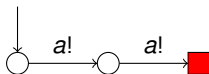


works for input determinate systems

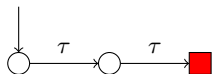
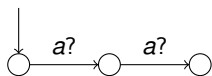
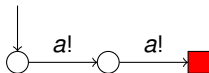
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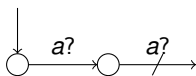
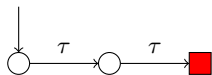
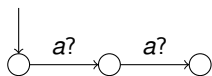
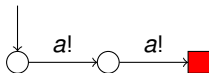


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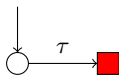
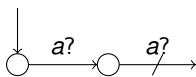
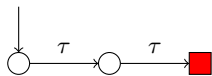
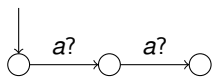
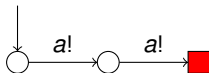




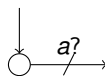
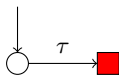
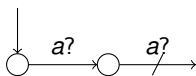
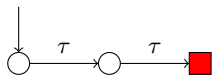
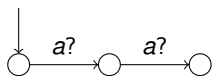
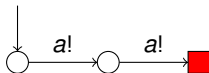
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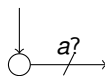
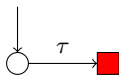
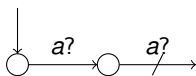
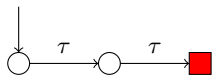
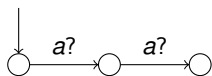
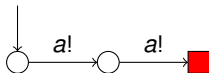
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# Precongruence

A preorder relation  $\sqsubseteq$  is a precongruence w.r.t.  $|$  if

$$Impl \sqsubseteq Spec \quad \Rightarrow \quad Impl | Env \sqsubseteq Spec | Env$$

# Refinement / Implementation

Basic requirement:

If the specification is error free, then the implementation has to be error free as well

Coarsest precongruence:  $\sqsubseteq^C$

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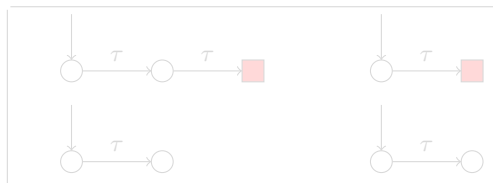
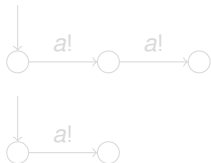
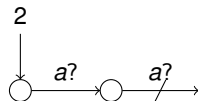
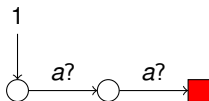
# Functions

- $prune : \Sigma^* \rightarrow \Sigma^*$ ,  $w \mapsto u$ , where  $w = uv$ ,  $u = \varepsilon \vee u \in \Sigma^* \cdot I$  and  $v \in O^*$
- $cont : \Sigma^* \rightarrow \mathfrak{P}(\Sigma^*)$ ,  $w \mapsto \{wu \mid u \in \Sigma^*\}$

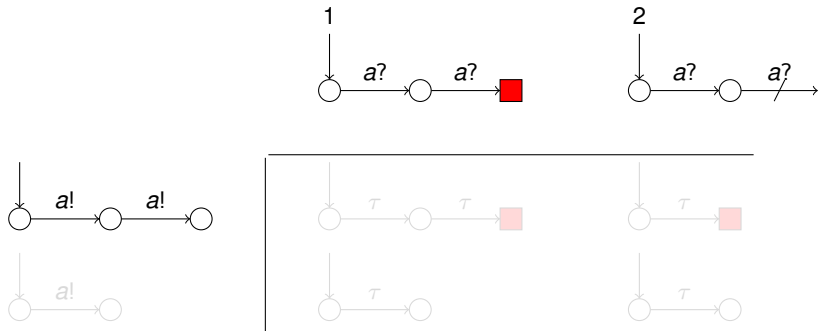
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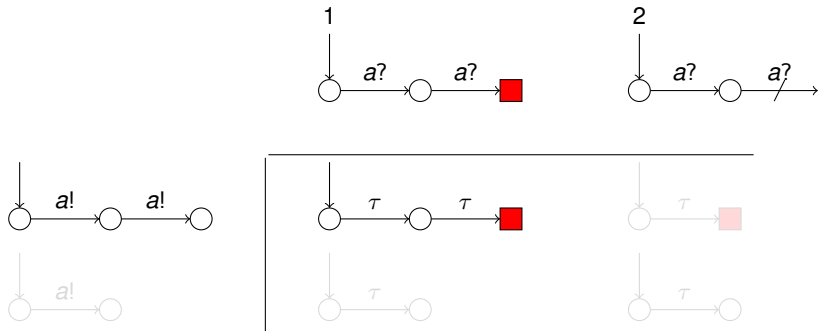
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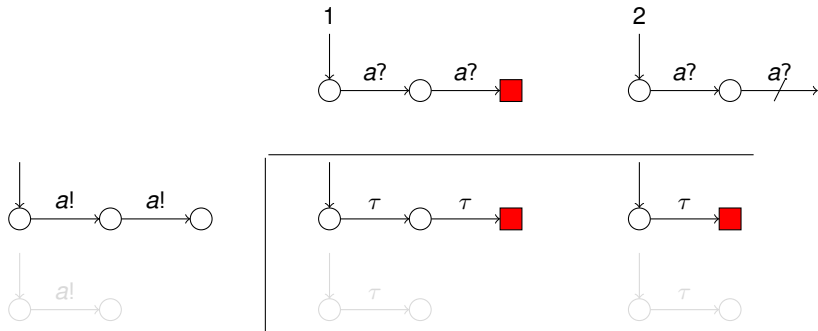


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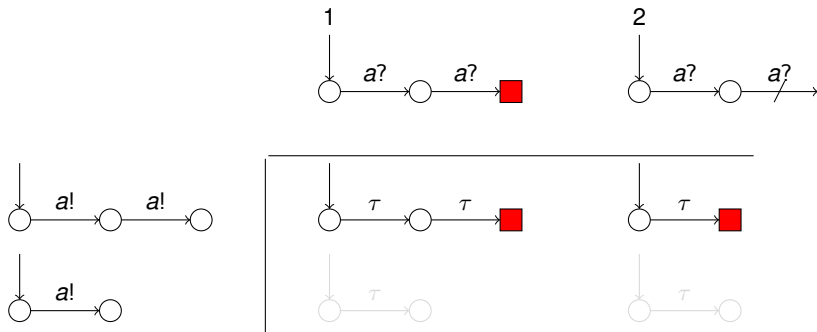




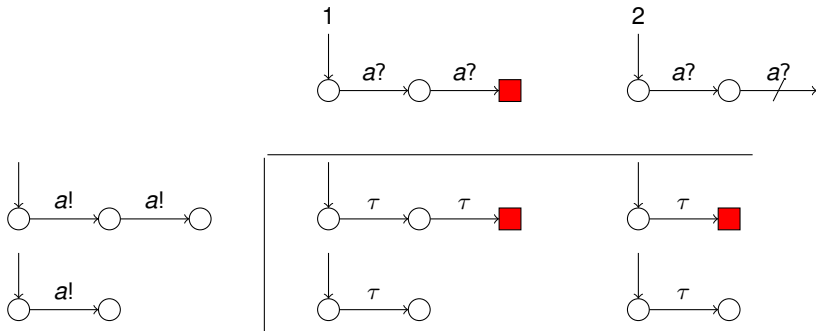
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# Traces and Semantics

- **Strict error traces:**  $StS(S) = \{w \in \Sigma^* \mid q_0 \xRightarrow{w} q \in E\}$
- Pruned error traces:  $PrT(S) = \{prune(w) \mid w \in StT(S)\}$
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## Local Error Semantics:

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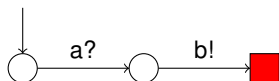
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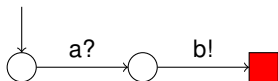
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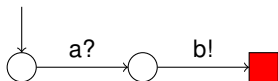
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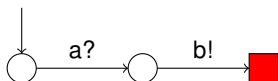
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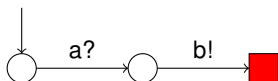
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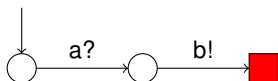
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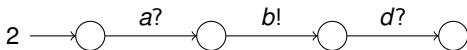
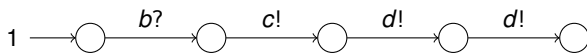
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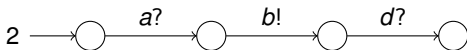
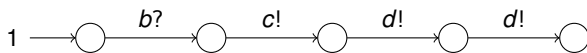
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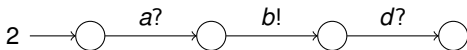
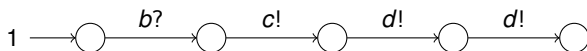
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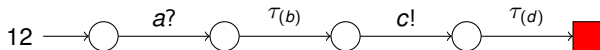
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- Assume  $Impl \sqsubseteq_{loc}^c Spec$
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- Associativity w.r.t.  $=_{loc}$
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# Notions of Error

Basic requirement:

If the specification is error free, then the implementation has to be error free as well

Notions of having an error:

- 1 An error state is reachable by locally controlled actions (internal and output)
- 2 **An error state is reachable by internal actions**
- 3 An error state is reachable at all

# Internal errors

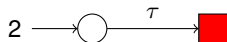
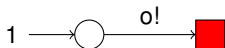
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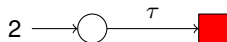
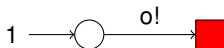
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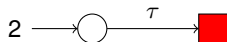
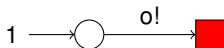
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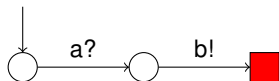
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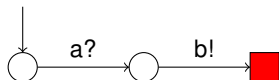
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 $PrP(S) = \{prune(w, X) \mid (w, X) \in StP(S)\}$
- Missing-input pairs:  
 $MIP(S) = \{(w, X) \mid w \in MIT(S), out(w) = X\}$
  
- Error pairs:  $EP(S) = cont(PrP(S)) \cup cont(MIP(S))$
- Error pair traces:  $EPT(S) = \{w \mid (w, out(w)) \in EP(S)\}$
- Error pair language:  $EPL(S) = L(S) \cup EPT(S)$

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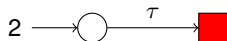
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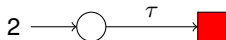


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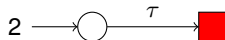
- $ET_1 = EL_1 = \Sigma^* = ET_2 = EL_2$
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# Internal vs. Local

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# Notions of Error

Basic requirement:

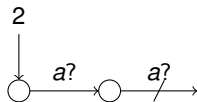
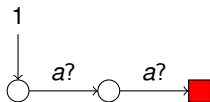
If the specification is error free, then the implementation has to be error free as well

Notions of having an error:

- 1 An error state is reachable by locally controlled actions (internal and output)
- 2 An error state is reachable by internal actions
- 3 **An error state is reachable at all**

# Missing inputs

Again local semantics do not suffice:  $ET_1 = \{aa\}\Sigma^* = ET_2$



# Pessimistic Semantics

- Continued pruned traces:

$$CPT(S) = cont(prune(StT(S)));$$

- Flooded missing-input traces:

$$MIC(S) = MIT(S) \cup CPT(S);$$

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Refinement preorder:

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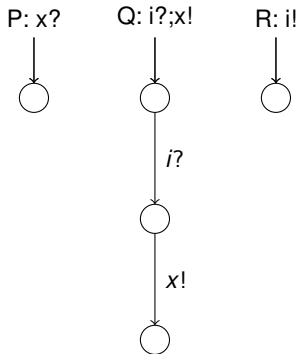
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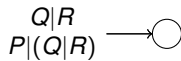
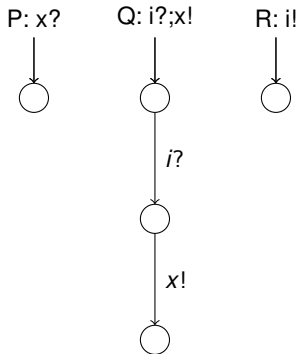
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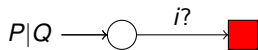
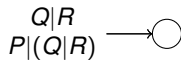
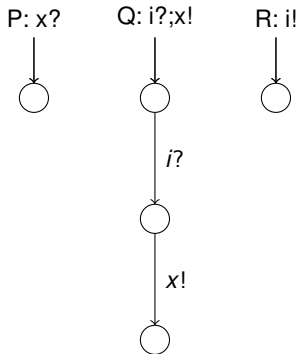
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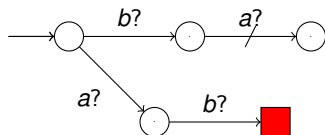
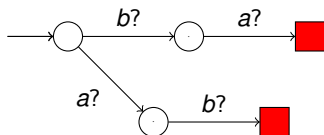
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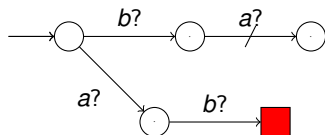
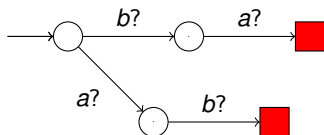


# Non-Coarsestness



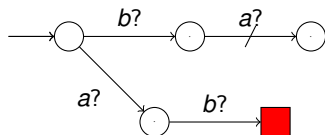
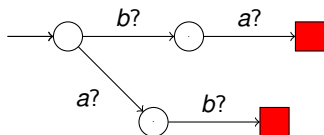
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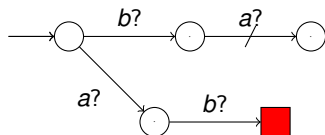
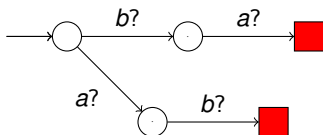
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- Unnecessarily complex



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Be optimistic!

Thank you